

Generic regularity of free boundaries for the obstacle problem

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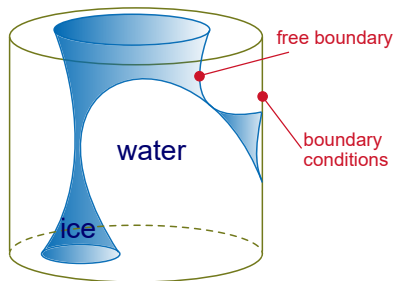
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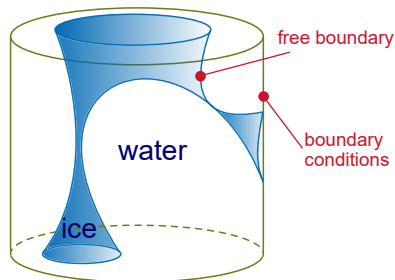
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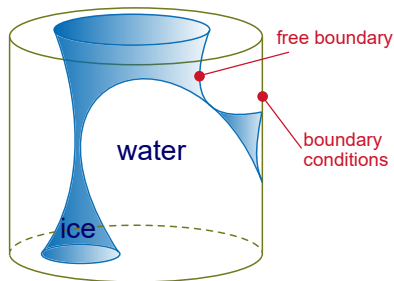
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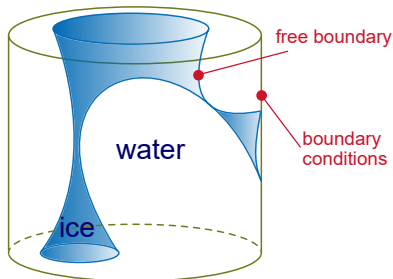
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- $u := \int_0^t \theta \geq 0$ solves:

$$u_t - \Delta u = -\chi_{\{u>0\}}$$



Free boundaries: The obstacle problem

The obstacle problem

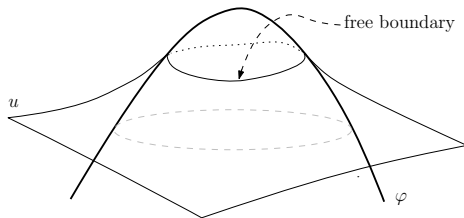
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Given $\varphi \in C^\infty$, minimize

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with the constraint $v \geq \varphi$



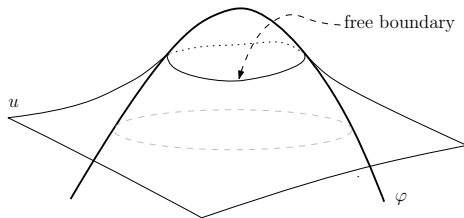
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The obstacle problem is

$$\left\{ \begin{array}{lll} v & \geq & \varphi \quad \text{in } \Omega \\ \Delta v & = & 0 \quad \text{in } \{x \in \Omega : v > \varphi\} \\ \nabla v & = & \nabla \varphi \quad \text{on } \partial\{v > \varphi\}, \end{array} \right.$$

(usually with boundary conditions $v = g$ on $\partial\Omega$)

$$\left\{ \begin{array}{lll} u & \geq & 0 \quad \text{in } \Omega, \\ \Delta u & = & 1 \quad \text{in } \{x \in \Omega : u > 0\} \\ \nabla u & = & 0 \quad \text{on } \partial\{u > 0\}. \end{array} \right. \longleftrightarrow \begin{array}{ll} u \geq 0 & \text{in } \Omega \\ \Delta u = \chi_{\{u > 0\}} & \text{in } \Omega \end{array}$$

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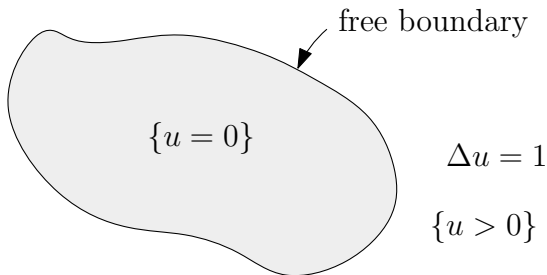
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The free boundary (FB) is the boundary $\partial\{u > 0\}$



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- Moreover, Stefan problem \longleftrightarrow parabolic obstacle problem !
- Thus, we want to understand better such problem.

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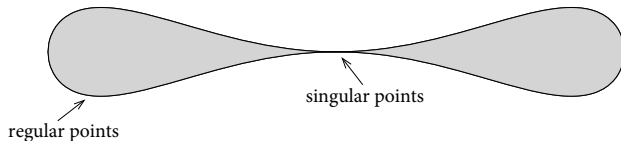
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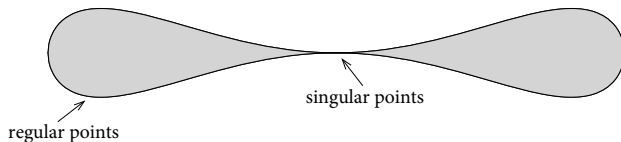


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- Furthermore, same results hold for the Stefan problem

To study the regularity of the FB, one considers blow-ups

$$u_r(x) := \frac{u(x_0 + rx)}{r^2} \longrightarrow u_0(x) \quad \text{in } C^1_{\text{loc}}(\mathbb{R}^n)$$

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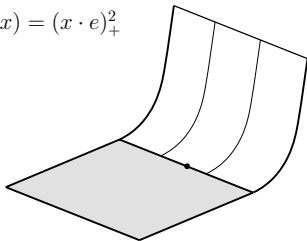
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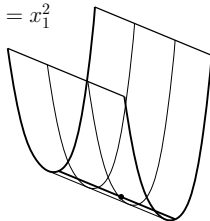
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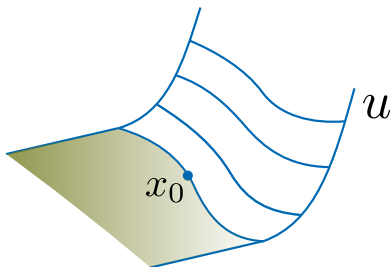
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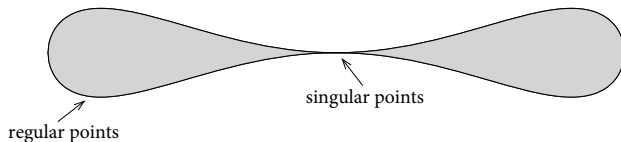
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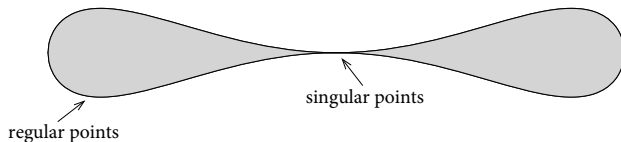
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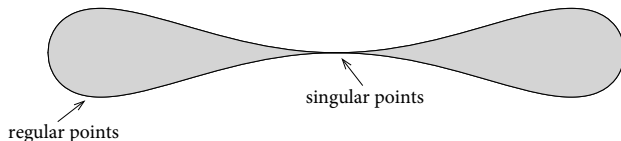
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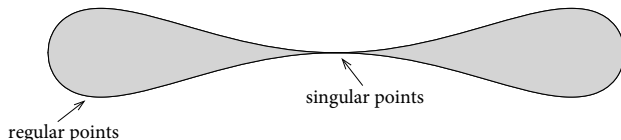
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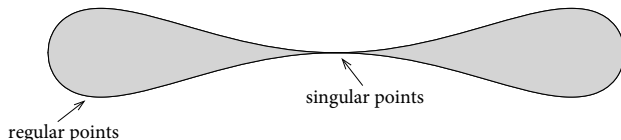
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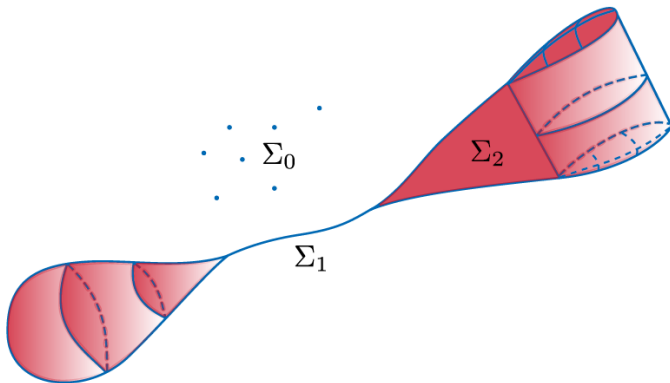
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- Figalli-Serra (2017): Outside a small set of lower dimension, singular points are contained in a $C^{1,1}$ manifold: $\boxed{O(|x - x_0|^3)}$

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A possible example of a free boundary in \mathbb{R}^3 with singularities:



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- Nothing known in higher dimensions!

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Theorem (Figalli-R.-Serra '19)

Let u_λ be the solution to the obstacle problem in \mathbb{R}^3 , with boundary data $g + \lambda$.

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- In other words: Generically, in \mathbb{R}^n , the singular set is very small!

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- 5) For almost every λ : In lower dimensions, we get no singular points; in higher dimensions we get an $(n - 4)$ -dimensional singular set.

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- At order $5 - \varepsilon$ we have to stop and we cannot control the errors anymore.

Lemma

We have a family of sets $E_\lambda \subset \mathbb{R}^n$ s.t.:

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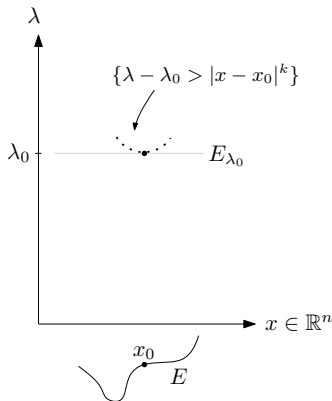
$$\dim_{\mathcal{H}}(E) \leq \beta$$

- For a certain $k > 0$, for any $x_0 \in E_{\lambda_0}$

$$\{\lambda - \lambda_0 > |x - x_0|^k\} \cap E_\lambda = \emptyset$$

Then, for almost every λ , we have

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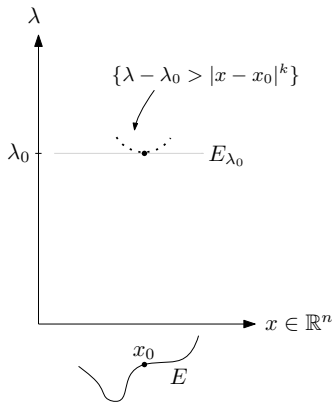
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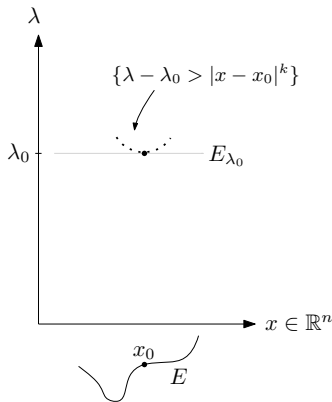
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- We need all dimension-reduction arguments for E , not only for each E_λ !



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Combining this with the previous GMT Lemma, we get the desired result. □

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- Is the $\frac{1}{2}$ sharp? We don't know, but it is critical in several ways.

Thank you!