Instability and non-uniqueness of Leray solutions of the forced Navier-Stokes equations, Part 3 ¹

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Main result

$$\begin{cases} \partial_t u + (u \cdot \nabla)u + \nabla p - \Delta u = f \\ \operatorname{div} u = 0 & \text{on } \mathbb{R}^3 \times [0, T] \\ u(\cdot, 0) = u_0 \end{cases}$$
(NS)

Theorem (Albritton-B.-Colombo '21, '22)

Let Ω be \mathbb{R}^3 , a smooth bounded domain, or \mathbb{T}^3 . Then, there exist u and \overline{u} , two distinct suitable Leray-Hopf solutions to (NS) with identical body force $f \in L^1_t L^2_x$ and $u(\cdot, 0) = \overline{u}(\cdot, 0) = 0$. When Ω is a bounded domain, u and \overline{u} satisfy no-slip boundary conditions and f is supported far away from the boundary.

Previous lectures

Theorem (Albritton-B.-Colombo '21)

There exist two distinct suitable Leray-Hopf solutions to (NS) with identical body force $f \in L^1_t L^2_x$ and $u(\cdot, 0) = \bar{u}(\cdot, 0) = 0$.

• Linear instability: There exists $\bar{U} \in C_c^{\infty}$ such that

$$\mathcal{L}_{\mathrm{ss}}: \mathcal{D}(\mathcal{L}_{\mathrm{ss}}) \subset L^2_{\sigma} \to L^2_{\sigma}$$

has a maximal unstable eigenvalue.

▶ Nonlinear instability: The unstable eigenvalue can be perturbed to \overline{U} , an unstable trajectory for (ssNS). In standard variables, $u(x, t) = \frac{1}{\sqrt{t}}U(\xi)$ provides a second solution to (NS) with body force *f* and $u(0, \cdot) = 0$.

Theorem (Linear instability)

There exists a divergence-free vector field $\overline{U} \in C_c^{\infty}(\mathbb{R}^3; \mathbb{R}^3)$ s.t. $\mathcal{L}_{ss} : D(\mathcal{L}_{ss}) \subset L^2_{\sigma}(\mathbb{R}^3; \mathbb{R}^3) \to L^2_{\sigma}(\mathbb{R}^3; \mathbb{R}^3)$

$$-\mathcal{L}_{ss}V = -\frac{1}{2}(1+\xi\cdot\nabla)V - \Delta V + \mathbb{P}(\bar{U}\cdot\nabla V + V\cdot\nabla\bar{U})$$

has a maximal unstable eigenvalue.

Theorem (Nonlinear instability)

Let $\lambda \in \mathbb{C}$, $\operatorname{Re}\lambda > 0$, be a maximal unstable eigenvalue of \overline{U} with eigenfunction $\eta \in H^k$ for all $k \in \mathbb{N}$. Set $U^{\operatorname{lin}}(\xi, \tau) = \operatorname{Re}(e^{\lambda \tau}\eta(\xi))$. There exist $T \in \mathbb{R}$ and a div-free vector field $U^{\operatorname{per}} : \mathbb{R}^3 \times (-\infty, T) \to \mathbb{R}^3$ such that

Regularity and decay:

$$\| {\it U}^{
m per}(\cdot, au)\|_{{\it H}^k} \lesssim {\it e}^{2a au}\,, \quad au \leq {\it T},\, k\geq 0$$

• $U := \overline{U} + U^{\text{lin}} + U^{\text{per}}$ solves

$$\partial_{\tau}U - \frac{1}{2}(1 + \xi \cdot \nabla)U - \Delta U + U \cdot \nabla U + \nabla P = F$$
 (ssNS)

Construction of a linear unstable backgrounds

Theorem (Albritton-B.-Colombo)

There exists a divergence-free vector field $\overline{U} \in C_c^{\infty}(\mathbb{R}^3; \mathbb{R}^3)$ s.t. the linear operator $\mathcal{L}_{ss} : D(\mathcal{L}_{ss}) \subset L^2_{\sigma}(\mathbb{R}^3; \mathbb{R}^3) \to L^2_{\sigma}(\mathbb{R}^3; \mathbb{R}^3)$

$$D(\mathcal{L}_{ss}) := \{ V \in L^2_{\sigma} : V \in H^2(\mathbb{R}^3), \, \xi \cdot \nabla U \in L^2(\mathbb{R}^3) \}, \\ -\mathcal{L}_{ss}U = -\frac{1}{2}(1 + \xi \cdot \nabla)U - \Delta U + \mathbb{P}(\bar{U} \cdot \nabla U + U \cdot \nabla \bar{U})$$

has an unstable eigenvalue.

Definition (Linear Instability)

We say that $\mathcal{L}_{ss}: D(\mathcal{L}_{ss}) \subset L^2_{\sigma} \to L^2_{\sigma}$ has an unstable eigenvalue if there exist

•
$$\lambda \in \mathbb{C}$$
 with $a := \operatorname{Re} \lambda > 0$

•
$$\eta \in H^k(\mathbb{R}^3; \mathbb{R}^3)$$
 for any $k > 0$, with div $\eta = 0$ such that

$$\mathcal{L}_{ss}\eta = \lambda\eta$$
.

Theorem (Albritton-B.-Colombo '22)

Let Ω be a smooth bounded domain, or \mathbb{T}^3 . Then, there exist u and \overline{u} , two distinct suitable Leray-Hopf solutions to (NS) with identical body force $f \in L^1_t L^2_x$, initial condition $u(\cdot, 0) = \overline{u}(\cdot, 0) = 0$, and no-slip boundary conditions.

Plan of the talk

- Linear instability and Vortex ring construction
- Gluing non-unique Navier-Stokes solutions
- Open questions

Linear instability and vortex ring construction

Construction of a linear unstable backgrounds

Theorem (Albritton-B.-Colombo)

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$$\mathcal{L}_{ss}\eta = \lambda\eta$$
.

2D Instability: Vishik's theorem

$$L^2_m(\mathbb{R}^2) := \bigotimes_{k=1}^\infty \{\omega \in L^2(\mathbb{R}^2) : \omega = f(r)e^{ikm\theta}\}.$$

Theorem (Vishik '18, ABCDGJK'21)

There exist $m \ge 2$ and a smooth decaying vortex

$$\bar{u}(x) = \zeta(r)x^{\perp}, \qquad \bar{\omega}(x) = g(r)$$

such that $\mathcal{L} : D(\mathcal{L}) \subset L^2_m(\mathbb{R}^2) \to L^2_m(\mathbb{R}^2)$,

$$\mathcal{L}\omega = -\zeta(\mathbf{r})\partial_{\theta}\omega - (\mathrm{BS}_{2}[\omega]\cdot\mathbf{e}_{r})g'(\mathbf{r}).$$

has an unstable eigenvalue.

How to build an unstable 3D-vortex ring

- Step 1: We truncate \bar{u} to get an unstable, compactly supported vortex
- Step 2: We use the truncate vortex as a radial profile of 3D-Axisymmetric-no-swirl velocity field
- Step 3: We show that the vortex ring inherits the instability of Vishik's vortex

Step 1: Compactly supported unstable vortex

Let $\lambda_{\infty} \in \mathbb{C} \cap \{ \text{Re} > 0 \}$ be an unstable eigenvalue of

$$\mathcal{L}\omega = -\zeta(\mathbf{r})\partial_{ heta}\omega - (\mathrm{BS}_2[\omega]\cdot\mathbf{e}_r)g'(\mathbf{r}),$$

where $u = \zeta(r)x^{\perp}$, $\omega = g(r)$ is Vishik's unstable vortex.

Proposition (Truncated unstable vortex)

For any $\varepsilon \in (0, \operatorname{Re}\lambda_{\infty})$, if $R \ge R(\varepsilon, u)$ the following holds. The linear operator

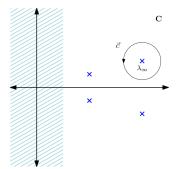
$$\mathcal{L}_R: D(\mathcal{L}_R) \subset L^2_m(\mathbb{R}^2) \to L^2_m(\mathbb{R}^2)$$

associated with the truncated vortex

$$\overline{u}_R(x) = \zeta(r)\chi_R(r)x^{\perp}, \qquad \overline{\omega}(x) = \operatorname{curl} \overline{u}_R(x) = g_R(r),$$

admits an unstable eigenvalue λ_R with $|\lambda_R - \lambda_{\infty}| \leq \varepsilon$.

Spectral projection



Spectral projection: Let ^c be a simple closed curve in ℂ,

$$\Pr_{\vec{c}}(\mathcal{L}) = \frac{1}{2\pi i} \int_{\vec{c}} \mathcal{R}(\lambda, \mathcal{L}) \, \mathrm{d}\lambda$$

is the spectral projection in the region enclosed by \vec{c} .

Resolvent:

$$R(\lambda,\mathcal{L}) = (\lambda - \mathcal{L})^{-1}$$

Let \vec{c} a simple closed curve enclosing λ_{∞} , we need to prove that

$$\operatorname{Pr}_{\vec{c}}(\mathcal{L}_R) \to \operatorname{Pr}_{\vec{c}}(\mathcal{L}), \quad \text{as } R \to \infty.$$

It is enough to show that

$$R(\lambda, \mathcal{L}_R) o R(\lambda, \mathcal{L})$$
, as $R \to \infty$, for any $\lambda \in \vec{c}$.

Spectral perturbation argument

We write

$$egin{aligned} \lambda - \mathcal{L}_{R} &= \lambda - \mathcal{L} + (\mathcal{L} - \mathcal{L}_{R}) \ &= (\lambda - \mathcal{L})[I + R(\lambda, \mathcal{L})(\mathcal{L} - \mathcal{L}_{R})] \ &= (\lambda - \mathcal{L}) + o(1) \,, \quad ext{as } R o \infty \,. \end{aligned}$$

Where we used that $\mathcal{L}_{R} \to \mathcal{L}$ in a suitable sense.

It is immediate to conclude that

$$R(\lambda, \mathcal{L}_R) o R(\lambda, \mathcal{L})$$
, as $R \to \infty$, for any $\lambda \in \vec{c}$.

Step 2: Lifting the truncated vortex to a vortex ring

Let $u(x) = \zeta(r)x^{\perp}$, $\omega = \operatorname{curl} u = g(r)$ be a vortex. Let

$$\mathcal{L}\omega = -\zeta(\mathbf{r})\partial_{\theta}\omega - (\mathrm{BS}_{2}[\omega]\cdot\mathbf{e}_{r})g'(\mathbf{r}),$$

be the associated linearized operator. We assume that

- Compactly supported: supp u, supp $\omega \subset B_1(0)$
- ▶ Instability: There exist $\lambda \in \mathbb{C} \cap \{ \text{Re} > 0 \}$ and $\rho \in L^2(\mathbb{R}^2)$ such that $\mathcal{L}\rho = \lambda \rho$.

Remark

supp $\rho \subset B_1(0)$ and λ is an isolated eigenvalue.

Axisymmetric-no-swirl structure

$$x = (r \cos \theta, r \sin \theta, z) \in \mathbb{R}^3$$

Axisymmetric-no-swirl vector fields:

$$U=U^r(r,z)e_r+U^z(r,z)e_z\,,$$

$$\operatorname{curl} U = -(\partial_z U^r - \partial_r U^z) e_{\theta} = -\Omega(r, z) e_{\theta}.$$

• We assume
$$\overline{U} = \overline{U}^r(r, z)e_r + \overline{U}^z(r, z)e_z$$
.

The space

 $L^2_{\mathrm{ans}}(\mathbb{R}^3) := \{ U \in L^2_{\sigma}(\mathbb{R}^3) : U \text{ is axisymmetric-no-swirl} \}$

is invariant under the action of

$$-\mathcal{L}_{ss}U = -\frac{1}{2}(1+\xi\cdot\nabla)U - \Delta U + \mathbb{P}(\bar{U}\cdot\nabla U + U\cdot\nabla\bar{U})$$

The 3D vortex ring

• Let $u, \omega = \operatorname{curl} u$ be the unstable compactly supported vortex,

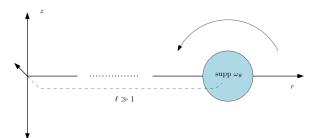
$$u(x) = u(x_1, x_2) = (u^1(x_1, x_2), u^2(x_1, x_2)), \quad x = (x_1, x_2) \in \mathbb{R}^2$$

• Let $\ell \gg 1$. We set

$$\tilde{U}(r,z) = u^1(r-\ell,z)e_r + u^2(r-\ell,z)e_z$$

Notice that

$$\operatorname{curl} \tilde{U} = -\omega(r-\ell,z)e_{\theta}$$
.



The 3D vortex ring

► Divergence:

div
$$\tilde{U} = \left(\partial_r + \frac{1}{r}\right) u^1 + \partial_z u^2 = \frac{1}{r} u^1 \ll 1$$
 if $\ell \gg 1$

▶ Correction of the divergence: There exists $V_{\ell} \in C^{\infty}_{c}(B_{2}; \mathbb{R}^{3})$ such that

$$\operatorname{div}(ilde U+V_\ell)=0\,,$$
 $V_\ell o 0\,,\quad ext{in } \mathcal{C}^k$ for all $k,$ as $\ell o\infty\,.$

Final vortex ring: For any $\ell \gg 1$ we set

 $ar{U}_\ell = ar{U} + V_\ell$.

Step 3: Instability of the vortex ring

Theorem (Instability of \bar{U}_{ℓ})

There exists ℓ_0 such that, if $\ell \geq \ell_0$ then the linear operator

$$-\mathcal{L}_{\mathrm{ss},\ell}U = -\frac{1}{2}(1+\xi\cdot\nabla)U - \Delta U + \mathbb{P}(\bar{U}_{\ell}\cdot\nabla U + U\cdot\nabla\bar{U}_{\ell}),$$

admits an unstable eigenvalue, i.e. there exist $\lambda_{\ell} \in \mathbb{C} \cap \{\text{Re} > 0\}$ and $\eta_{\ell} \in H^k$ for any $k \geq 0$, such that $\mathcal{L}_{\text{ss},\ell}\eta_{\ell} = \lambda_{\ell}\eta_{\ell}$.

Since \overline{U}_{ℓ} is axisymmetric-no-swirl, we have

$$\mathcal{L}_{\mathrm{ss},\ell}: D(\mathcal{L}_{\mathrm{ss},\ell}) \subset L^2_{\mathrm{ans}} \to L^2_{\mathrm{ans}}$$

and $\eta_{\ell} \in L^2_{ans}$ as well.

Idea of proof

First reduction: It is enough to prove instability for the operator

$$-\mathcal{L}_{\mathrm{st},\ell}U = \mathbb{P}(\bar{U}_{\ell}\cdot\nabla U + U\cdot\nabla\bar{U}_{\ell}).$$

Second reduction: We study the spectral problem in vorticity formulation

$$\mathcal{L}_{\mathrm{vor},\ell}: \mathcal{D}(\mathcal{L}_{\mathrm{vor},\ell}) \subset L^2_{\mathrm{aps}} \to L^2_{\mathrm{aps}}$$

▶ Key observation: When $\ell \gg 1$ the operator $\mathcal{L}_{vor,\ell}$ is "close" to

$$\mathcal{L}\omega = -\zeta(\mathbf{r})\partial_{\theta}\omega - (\mathrm{BS}_{2}[\omega]\cdot\mathbf{e}_{\mathbf{r}})g'(\mathbf{r}).$$

First reduction

▶ Perturbative argument: If $\mathcal{L}_{st,\ell}U = -\mathbb{P}(\bar{U}_{\ell} \cdot \nabla U + U \cdot \nabla \bar{U}_{\ell})$ admits an unstable eigenvalue, then there exists $\beta \ll 1$ such that

$$-\mathcal{L}_{\beta}U = -\beta\left(\frac{1}{2}(1+\xi\cdot\nabla)U + \Delta U\right) + \mathbb{P}(\bar{U}_{\ell}\cdot\nabla U + U\cdot\nabla\bar{U}_{\ell}).$$

▶ By replacing \overline{U}_{ℓ} with $\frac{1}{\beta}\overline{U}_{\ell}$, we get that $\mathcal{L}_{ss,\ell}$ admits an unstable eigenvalue.

Second reduction

We set

$$\mathcal{L}_{\mathrm{vor},\ell} := \mathrm{curl} \circ \mathcal{L}_{\mathrm{st},\ell} \circ \mathrm{BS}_{\mathrm{3}d} : \mathcal{D}(\mathcal{L}_{\mathrm{vor},\ell}) \subset \mathcal{L}^2_{\mathrm{aps}} \to \mathcal{L}^2_{\mathrm{aps}} \,.$$

$$\mathcal{L}^2_{\mathrm{aps}}(\mathbb{R}^3) \sim \mathcal{L}^2(\mathbb{R}_+ imes \mathbb{R})\,, \quad -\omega(r,z) \, m{e}_ heta \sim \omega(r,z)\,,$$

hence,

$$\mathcal{L}_{\mathrm{vor},\ell}: \mathcal{D}(\mathcal{L}_{\mathrm{vor},\ell}) \subset L^2(\mathbb{R}_+ \times \mathbb{R}) \to L^2(\mathbb{R}_+ \times \mathbb{R}).$$

 $\blacktriangleright \ \ {\rm curl} \ \bar{\pmb{U}}_\ell = -\bar{\omega}_\ell \pmb{e}_\theta, \, \omega \in L^2(\mathbb{R}_+ \times \mathbb{R}),$

$$\begin{cases} -\mathcal{L}_{\mathrm{vor},\ell}\omega := (\bar{U}_{\ell} \cdot \nabla)\omega + (U \cdot \nabla)\bar{\omega}_{\ell} - \frac{\bar{U}_{\ell}}{r}\omega - \frac{U'}{r}\bar{\omega}_{\ell} \\ U = \mathrm{BS}_{3d}[-\omega \boldsymbol{e}_{\theta}] \,. \end{cases}$$

Convergence to Vishik's operator

$$\begin{cases} -\mathcal{L}_{\mathrm{vor},\ell}\omega := (\bar{U}_{\ell} \cdot \nabla)\omega + (U \cdot \nabla)\bar{\omega}_{\ell} - \frac{\bar{U}_{\ell}'}{r}\bar{\omega}_{\ell} \\ U = \mathrm{BS}_{\ell}[\omega] \,. \end{cases}$$

$$\blacktriangleright \ (\bar{U}_{\ell} \cdot \nabla) \omega \to (u \cdot \nabla) \omega$$

$$\blacktriangleright \ \bar{\omega}_{\ell} \to \omega = \operatorname{curl} \boldsymbol{U}$$

$$\blacktriangleright -\frac{\bar{U}_{\ell}^{r}}{r}\omega - \frac{U^{r}}{r}\bar{\omega}_{\ell} \to \mathbf{0}$$

$$\blacktriangleright BS_{\ell}[\omega] \to BS_{2d}[\omega]$$

In conclusion:

$$\mathcal{L}_{\mathrm{vor},\ell}\omega
ightarrow \mathcal{L}\omega = -\zeta(\mathbf{r})\partial_{\theta}\omega - (\mathrm{BS}_{2}[\omega]\cdot\mathbf{e}_{\mathbf{r}})g'(\mathbf{r})$$

Convergence of BS laws

• Let $\omega \in L^2(\mathbb{R}_+ \times \mathbb{R})$, we have

$$BS_{3d}[-\omega \boldsymbol{e}_{\theta}] = -\partial_{z}\psi \,\boldsymbol{e}_{r} + \left(\partial_{r} + \frac{1}{r}\right)\psi \,\boldsymbol{e}_{z} \,.$$

where, the stream function ψ is obtained by solving

$$\partial_r^2 \psi + \frac{1}{r} \partial_r \psi - \frac{1}{r^2} \psi + \partial_z^2 \psi = \omega \quad \text{ in } \mathbb{R}_+ \times \mathbb{R} \,.$$

• Let $\omega \in L^2(\mathbb{R}^2)$, we have

$$BS_{2d}[\omega] = -\partial_{x_2}\psi \,\boldsymbol{e}_1 + \partial_{x_1}\psi \,\boldsymbol{e}_2 \,.$$

where, the stream function ψ is obtained by solving

$$\partial_{x_1}^2 \psi + \partial_{x_2}^2 \psi = \omega$$
 in \mathbb{R}^2 .

Gluing non-unique Navier-Stokes solutions

Gluing non-unique Navier-Stokes solutions

Theorem (Albritton-B.-Colombo '22)

Let Ω be a smooth bounded domain, or \mathbb{T}^3 . Then, there exist u and \overline{u} , two distinct suitable Leray-Hopf solutions to (NS) with identical body force $f \in L^1_t L^2_x$, initial conditions $u(\cdot, 0) = \overline{u}(\cdot, 0) = 0$, and no-slip boundary conditions.

▶ The non-uniqueness in \mathbb{R}^3 is driven by the instability of

$$\bar{u}(x,t) = \frac{1}{\sqrt{t}} \bar{U}\left(\frac{x}{\sqrt{t}}\right) \,.$$

The non-uniqueness "emerges" from the irregularity at the space-time origin and is expected to be local.

Gluing non-unique Navier-Stokes solutions

Assume that $B_{1/2}(0) \subset \Omega$.

For $t \ll 1$, we have

 $\operatorname{supp} \overline{u}(t,\cdot), \operatorname{supp} f(t,\cdot) \subset B_{1/2}(0) \subset \Omega$.

Hence, (\bar{u}, f) satisfies (NS) in Ω with no-slip boundary conditions.

- The second solution $u = \overline{u} + u^{\text{lin}} + u^{\text{per}}$ is supported on the hole \mathbb{R}^3 .
- Goal: We want to build a new solution v to (NS) in Ω , s.t.
 - v satisfies no-slip boundary conditions
 - ▶ $v \sim u$ in $B_{1/10}(0) \subset \Omega$

The main Ansatz

 $\mathbf{v}(\mathbf{x},t) = \bar{\mathbf{u}}(\mathbf{x},t) + \eta(\mathbf{x})\varphi(\mathbf{x},t) + \psi(\mathbf{x},t), \quad \mathbf{x} \in \Omega, \ t \in (0,t_0).$

> η is a smooth cut-off function, i.e.

$$\eta = 1$$
 in $B_{1/9}(0)$, $\eta = 0$ in $\Omega \setminus B_{1/7}(0)$.

- φ is the inner solution, i.e. it will satisfy $\varphi \sim u$.
- \blacktriangleright ψ is the outer solution, it satisfies no-slip boundary conditions.

Inner and outer equations

We plug the Ansatz

$$\mathbf{v}(\mathbf{x},t) = \bar{\mathbf{u}}(\mathbf{x},t) + \eta(\mathbf{x})\varphi(\mathbf{x},t) + \psi(\mathbf{x},t)$$

into (NS) and we decouple the system as follows.

▶ Inner equation: In self-similar variables, $\xi = x/\sqrt{t}$, $\tau = \log(t)$,

$$\varphi(x,t) = \frac{1}{\sqrt{t}} \Phi(\xi,\tau), \quad \psi(x,t) = \frac{1}{\sqrt{t}} \Psi(\xi,\tau), \quad \eta(x) = N(\xi,\tau)$$

We have

$$\partial_{ au} \Phi - \mathcal{L}_{ss} \Phi + \Phi \cdot \nabla (\Phi N) + \operatorname{div}(\tilde{N} \Psi \otimes \Phi + \tilde{N} \Phi \otimes \Psi)
onumber \\ + \bar{U} \cdot \nabla \Psi + \Psi \cdot \nabla \bar{U} + \nabla \Pi = 0 \,,$$

where $\tilde{N}(\xi, \tau) = N(\xi/3, \tau)$.

Outer equation:

$$\partial_t \psi - \Delta \psi + \psi \cdot \nabla \psi + \nabla \pi - \varphi \Delta \eta - 2 \nabla \varphi \cdot \nabla \eta + (\psi \cdot \nabla \eta) \varphi = 0$$

div $\psi = -\nabla \eta \cdot \varphi$

Inner equation

$$\partial_{\tau} \Phi - \mathcal{L}_{ss} \Phi + \Phi \cdot \nabla(\Phi N) + \operatorname{div}(\tilde{N} \Psi \otimes \Phi + \tilde{N} \Phi \otimes \Psi)$$

 $+ \overline{U} \cdot \nabla \Psi + \Psi \cdot \nabla \overline{U} + \nabla \Pi = 0,$

• We solve in the whole \mathbb{R}^3 using linear instability and the Ansatz

$$\Phi = \Phi^{lin} + \Phi^{per} \,.$$

- The orange terms are linear, but small.
- ► The purple terms are non-linear.

Outer equation

$$\partial_t \psi - \Delta \psi + \psi \cdot \nabla \psi + \nabla \pi - \varphi \Delta \eta - 2 \nabla \varphi \cdot \nabla \eta + (\psi \cdot \nabla \eta) \varphi = 0$$

div $\psi = -\nabla \eta \cdot \varphi$

- It amounts to solve the Navier-Stokes equation with inhomogeneous divergence and no-slip boundary conditions.
- The purple terms are treated as perturbations. Small because:
 - ► All the derivatives of η are concentrated on $A = B_{1/7}(0) \setminus B_{1/9}(0)$
 - Φ decays at infinity, hence $\varphi(x, t) = \frac{1}{\sqrt{t}} \Phi(x/\sqrt{t}, \log(t))$ is small in *A*, when $t \ll 1$.

Functional setting and fixed point argument

For $\overline{t} > 0$, $\overline{\tau} = \log(\overline{t})$, and $\alpha, \beta > 0$, we define the norms

$$\begin{split} \|\Phi\|_{X^{\alpha}_{\tilde{\tau}}} &:= \sup_{\tau \leq \tilde{\tau}} e^{-\tau \alpha} \|\Phi(\cdot, \tau)\|_{L^{\infty}_{\mathsf{w}}} \\ \|\psi\|_{Y^{\beta}_{\tilde{t}}} &:= \sup_{s \in (0, \tilde{t})} s^{-\beta} \|\psi(\cdot, s)\|_{L^{\infty}(\Omega)} \,. \end{split}$$

Fixed-point argument in the space

$$Z_{\bar{t}}^{\alpha,\beta} := X_{\bar{\tau}}^{\alpha} \times Y_{\bar{t}}^{\beta}.$$

Key ingredients: Weighted semigroup estimate

$$\| e^{ au \mathcal{L}_{\mathrm{ss}}} \mathbb{P} \operatorname{div} \|_{L^p_{w} o L^\infty_{w}} \leq C(
ho, \delta) au^{-(rac{1}{2} + rac{3}{2
ho})} e^{(a+\delta) au} ,$$

for any $p \in (3, +\infty]$, $\delta > 0$.

Conclusions

Weak solutions to the forced (NS) in the energy class, i.e. Leray solutions, are not unique.

► The non-uniqueness in \mathbb{R}^3 is driven by extreme the instability of a self-similar solution

$$\bar{u}(x,t) = \frac{1}{\sqrt{t}}\bar{U}\left(\frac{x}{\sqrt{t}}\right),$$

in full agreement with [Jia-Sverak' 14] and [Sverak-Guillod '18].

The non-uniqueness "emerges" from the irregularity at the space-time origin shows a certain locality and robustness.

Open problems

- Is it possible to remove the force?
- There should be many unstable profiles U. How generic are they? Is there an easier way to find them?
- Gluing non-unique solutions to the Euler equations?

Thank you for your attention!